



Bupa get.with.the Challenge 2 – avoid items PROGRAM **Example grid layout:** There are some items which we only want to eat as a treat every so often, so which aren't OK for today's healthy lunch. Can you program the Robot to miss these items? 1. Designer: Choose where to add in the 'not OK' items. Plan or design the algorithm as before, making sure to go around the 'not OK' items to get to the 'finish' item (the wrap). 2. Writer: Record the algorithm on the whiteboard using forward, left and right arrows. It will probably be a bit more complicated than last time! 3. Robot: Use the whiteboard to follow the algorithm to test it. Did you go wrong? Debug if needed and try again.

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Challenge 3 – creative coding!

Now, can you use your imaginations to think of some other things to include in your algorithm?

- Maybe you can add in some other food items for our healthy lunch today, and design a route for the Robot to collect them all?
- Could you create a specific instruction to 'pick up' items? What would this look like in the algorithm?
- · Maybe the Robot can jump over 'not OK' items?
- Maybe they should do a happy dance when they've successfully collected the 'OK' items?

What other creative coding can you think of?

- **1. Designer:** Plan what steps to add in and where in the algorithm. You can use one of your blank squares to write/draw on, or cut up some paper.
- 2. Writer: Record the algorithm on the whiteboard make up new pictures for the new actions.
- **3. Robot:** Use the whiteboard to follow the algorithm to test it. Debug if needed and try again.

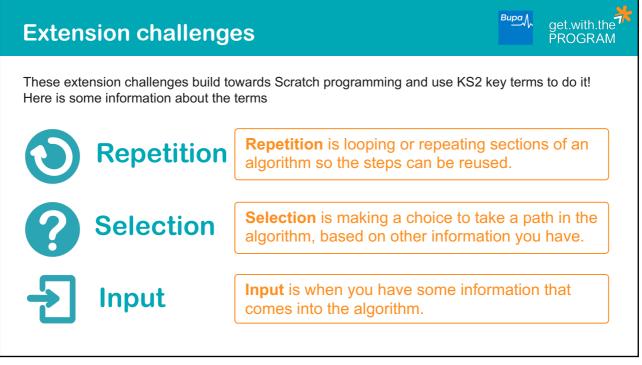
Example grid layout:

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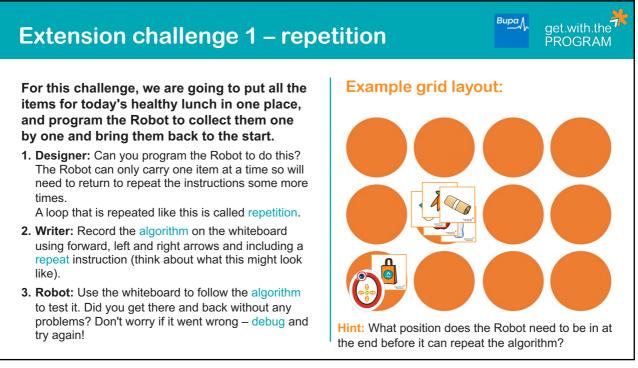
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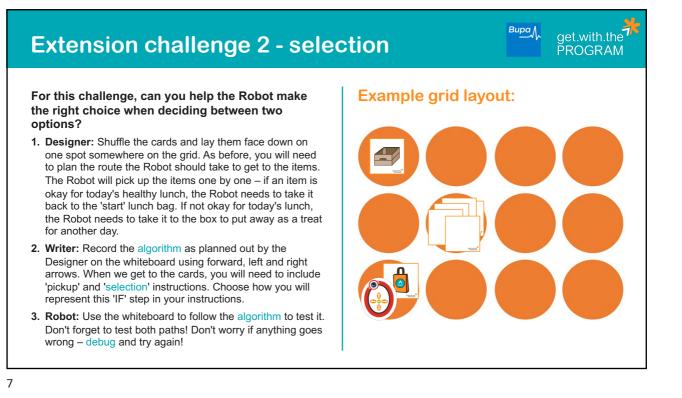
PROGRAM









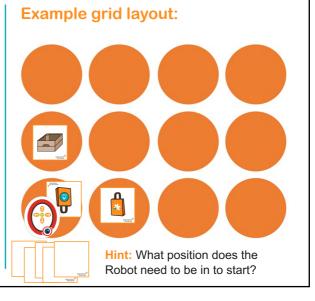


Extension super challenge – with added input

This challenge builds on the previous two extension challenges (repetition and selection), with added input:

For this challenge the Designer or Writer is going to be in charge of input - decide who it will be before you start. When the algorithm begins, you will need to stand next to the start and hand the Robot the cards one by one (this is the input). When the Robot is handed a card, they must decide whether it is okay for today's healthy lunch, and take it to the new lunch bag, or not okay for today's lunch, in which case it goes into the box for later.

- Designer: Place the practice Robot on the 'start' bag and put the other lunch bag and treats box nearby. Hand all the food item cards face down to the person controlling the input. Plan the route (algorithm) the Robot takes to both the lunch bag and treats box
- 2. Writer: Record the algorithm on the whiteboard. You will need to use an 'IF' step at the beginning (for selection), then use forward, left and right arrows to get to the bag or box, and include a repetition or loop step at the end. What might these look like?
- Robot: Turn over the card when you are handed it and use the 'IF' step on the whiteboard to decide whether to take it to the lunch bag or box. Follow the algorithm to test it. Debug if needed.



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